

VIBRATION TACHOMETER RVM-4000

1. FEATURES

- * In accordance with ISO 2954, used for periodic measurements, to detect out-of-balance, misalignment and other mechanical faults in rotating machines.
- * specially designed for easy on site vibration measurement of all rotating machinery for quality control, commissioning, and predictive maintenance purposes.
- * Multifunctional, one instrument combines Photo Tachometer & Contact Tachometer. Be able to measure rotation rate RPM(r/min) & Frequency Hz.
- * Individual high quality accelerometer for accurate and repeatable measurements.
- * Bearing condition monitoring function
- * LCD digital display.
- * Lightweight and easy to use.
- * Wide frequency range (10Hz. to 10kHz.) in acceleration mode.
- * Automatic power shut off to conserve power.
- * AC output socket for headphones and recording.

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- * Optional headphones for use as electronic stethoscope.
- * Can communicate with PC computer for statistics and printing by the optional cable and the software for USB interface.

2. SPECIFICATIONS

- Display: 4 digits, 18 mm LCD
Measured values and makers (units, 10, and battery symbol)
- Transducer :
Piezoelectric accelerometer
- Parameters measured:**
Velocity, Acceleration, and displacement
- Measuring range :
Velocity : 0.01-400.0 mm/s true RMS
Acceleration :
0.1-400.0m/s² equivalent peak
Displacement :
0.001-4.000mm equivalent pk-pk
- Frequency range for measuring:**
Acceleration : 10Hz. to 1kHz. In '1' mode
10Hz. to 10kHz. In '10' mode for bearing condition check
Velocity : 10Hz. to 1kHz.
Displacement : 10Hz. to 1kHz.

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Rotation Rate Range:

60~99,990RPM(r/min)
(Reading should be multiplied by 10 if the display shows '10')

Frequency Range: 1~20,000Hz
(Reading should be multiplied by 10 if the display shows '10')

Accuracy: ±(5%n+2) digits

PC interface: USB

Output: AC output 2.0V peak full scale
(load resistance: above 10k)

Operating conditions:

Temperature : 0-50 °C

Humidity : below 90% RH

Power supply:

4x1.5 V AA size batteries

Dimensions:

140x72x34mm

Weight:380g (not including batteries)

Accessories included :

Powerful rare earth magnet.....1 pc.

Accelerometer.....1 pc.

Stinger probe (Cone).....1 pc.

Stinger probe (Ball).....1 pc.

Contact Tachometer Sensor.....1 pc.

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- Photo Tachometer Sensor.....1 pc.
 - Reflective Tape Marks (350mm)
 - Carrying case.....1 pc.
 - Operation manual.....1 pc.
- Optional accessories:
Headphones for use as electronic stethoscope
Cable and software for USB

3. FRONT PANEL DESCRIPTIONS



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- 3-1 Display
- 3-2 Accelerometer
- 3-3 Input Connector
- 3-4 Hold key
- 3-5 Power Key
- 3-6 Metric/Imperial conversion key
- 3-7 Function key
- 3-8 Filter key
- 3-9 Sound key
- 3-10 Jack for the headphone
- 3-11 USB interface
- 3-12 Battery cover
- 3-13 Photo tachometer sensor
- 3-14 Contact tachometer sensor

4. VIBRATION MEASURING PROCEDURE

- 4.1 Connect the Accelerometer to the input connector and turn it until the connector locks in position.
- 4.2 Mount the accelerometer at the measurement point using the powerful magnet supplied, ensuring that the mounting surface is clean and flat, or use direct stud mounting if this is available.
- 4.3 Depress the power key and release to power on the meter.

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- 4.4 Each time the Function key is depressed and released quickly, the meter will step to the next vibration measurement parameter with the corresponding unit showing on the display.

- 4.5 When several machinery or bearings are used under the same operating conditions, evaluation can be carried out by listening to the audio signals to determine changes. This method will help to locate the defective machinery or bearing quickly. Measure all machines at the same points and compare the results. The sound volume can be adjusted by Sound key. There are 8 levels from 1 to 8. Every time depressing and releasing the sound key quickly, the sound level will increase 1. The larger the sound level number, the louder the listening sound.

5. PHOTO TACHOMETER MEASURING PROCEDURE

- 5.1 Connect the Photo tachometer sensor to the input connector and turn it until the connector locks in position.
- 5.2 Apply a reflective mark to the object

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being measured.

- 5.3 Press the Function key, when 'RPM' or 'Hz F' is displayed, it is in rotation rate measurement or frequency measurement. The Photo tachometer sensor emits a visible light beam. Align the visible light beam with the applied target, the reading is on the display.

6. CONTACT TACHOMETER MEASURING PROCEDURE

- 6.1 Connect the Contact tachometer sensor to the input connector and turn it until the connector locks in position.
- 6.2 Press the Function key, when 'RPM' or 'Hz F' is displayed, it is in rotation rate measurement or frequency measurement. Lightly pressing the RPM Adapter against the center hole on the rotating hole, the reading is on the display.

5. CONSIDERATIONS

5.1 Which Parameters Should be Measured?

Acceleration, velocity, and displacement are the three tried and tested parameters, which give accurate

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and repeatable results. Other measurement parameters have yet to prove themselves to be as reliable, accurate, and repeatable.

Acceleration is normally measured in m/s² peak (meters per second squared) has excellent high frequency measurement capabilities, and is therefore very effective for determining faults in bearings or gearboxes.

Velocity is the most commonly used vibration parameter. It is used for vibration severity measurements in accordance with ISO 2372, BS 4675 or VDI 2056, which are guidelines for acceptable vibration levels of machinery in different power categories. These are presented as a table in section 4 of this manual. Velocity is typically measured in cm/s RMS (centimeters or millimeters per second).

Note: This instrument measures in cm/s. If you are more familiar with measurements in mm/s, or wish to compare your measured values directly

with the vibration severity chart in section 4, multiply the displayed value by 10.

Displacement is typically used on low-speed machines because of its good low frequency response, and is relatively ineffective when monitoring bearings. Units are typically microns or mm equivalent peak-peak.

5.2 An Introduction To Vibration Measurement

Vibration is a reliable indicator of the mechanical health or condition of a particular machine or product. An ideal machine will have very little or no vibration indicating that the motor, as well as peripheral devices such as gearboxes, fans, compressors, etc., are suitably balanced, aligned, and well installed.

In practice, a very high percentage of installations are far from ideal, the results of misalignment and imbalance exerting added strain on supporting components such as bearings. Eventually this lead to added stress and wear on critical

A. Rank of machine vibration (ISO 2372)

Vibratio amplitude Vibration velocity V rms (mm/s)	Machine sort			
	I	II	III	IV
0-0.28	A	A		
0.28-0.45				
0.45-0.71				
0.71-1.12	B	B	B	B
1.12-1.8				
1.8-2.8	C	C	C	C
2.8-4.5				
4.5-7.1				
7.1-11.2	D	D	D	D
11.2-18				
18-28				
28-45				
>45				

Note:

- (1) Class I is small motor (power less than 15 kw). Class II is medium motor (power between 15 ~75kw). Class III is high power motor (hard base). Class IV is high power motor (stretch base)
- (2) A,B,C,D are vibration Rank. 'A' means good, 'B' means satisfying, 'C' means not satisfying, 'D' means forbidden.

components, resulting in inefficiency, heat generation and breakdowns. This often occurs at the most inconvenient or uneconomical times, causing costly production downtime. As parts of mechanical equipment wear and deteriorate, the equipment vibration increases. Vibration measurement is therefore a powerful aid in the predictive maintenance of such equipment, reducing downtime and assisting in the smoother running of the plant or factory.

Unscheduled breakdowns result in production losses and the faulty equipment is usually repaired hastily to get production going as quickly as possible. Under these stressful conditions staff are not always able to do repairs correctly regardless of how conscientious they are, resulting in a high probability of further early equipment failure.

By implementing a predictive maintenance program with regular measurements of critical factors like vibration, downtime can not only be reduced, but planned maintenance is more effective, resulting in

Vibration velocity should be taken from the three perpendicular axes on the motor shell.

B.ISO/IS2373 Motor quality standard according as vibration velocity

Quantity rank	Rev (rpm)	H: high of shaft (mm)		
		Maximum vibration velocity (rms)		
		(mm/s)		
		80<H<132	132<H<225	225<H<400
Normal (N)	600-3600	1.8	2.8	4.5
Good (R)	600-1800	0.71	1.12	1.8
	1800-3600	1.12	1.8	2.8
Excellent (S)	600-1800	0.45	0.71	1.12
	1800-3600	0.71	1.12	1.8

Limit of rank 'N' is suitable for common motor. When the request is higher than that in the table, limit can be gotten by dividing the limit of rank 'S' with 1.6 or multiples of 1.6.

C. Maximum vibration of motor that power larger than 1 horsepower (NEMA MG1-12.05)

improved product quality and greater productivity.

Continuous monitoring and trending of vibration levels over a time period is therefore a valuable addition to a machine's historical record.

5.3 What is a Trend?

A trend is an indication of the way in which a monitored vibration parameter behaves over time. If regular vibration measurements are taken and plotted over a period of time, the resulting graph shows the progress or deterioration of a particular machine.

Typically this will have the general shape shown in the diagram below, regardless of the type of machine being considered. For a short time after installation, whether it is a new or a repaired machine, vibration levels may fall slightly as the machine is run in, followed by a long period of unchanging levels during the machine's normal operating lifetime. Then comes a period of rising levels as machine parts wear out prior to

Rev (rpm)	Displacement (P - P) (um)
3000-4000	25.4
1500-2999	38.1
1000-1499	50.8
≤ 999	63.6

* For AC motor, rev is maximum synchronous rev. For DC motor, it is maximum power rev. For motor in series, it is work rev.

D. Maximum vibration of high power induction drive motor(NEMA MG1-20.52)

Rev (rpm)	Displacement (P -P) (um)
≥ 3000	25.4
1500-2999	50.8
1000-1499	63.6
≤ 999	76.2

National Electric Manufacturers Association (NEMA) Establishes two standards above.